

# Statistical Tests for the Detection of the Arrow of Time in Vector Autoregressive Models

Pablo Morales-Mombiela, Daniel Hernández-Lobato and Alberto Suárez  
Escuela Politécnica Superior, Universidad Autónoma de Madrid, Spain



## Causal Discovery in the Context of Multi-dimensional Time-series

Given a sample of a stationary multi-variate time series

$$\mathbf{X}_1, \mathbf{X}_2, \dots, \mathbf{X}_N, \quad (1)$$

we analyze if this sequence is in the correct chronological order or its time ordering has been reversed. This is a particular case of the general causal inference problem. In the one-dimensional case it has been shown that under a stationary AR model of the form:

$$\mathbf{X}_t = \phi \mathbf{X}_{t-1} + \epsilon_t, \quad \epsilon_t \perp \mathbf{X}_{t-1}, \quad (2)$$

with non-Gaussian i.i.d. noise  $\epsilon_t$ , the residuals in the backward time direction

$$\tilde{\epsilon}_t \equiv \mathbf{X}_t - \phi \mathbf{X}_{t+1}, \quad t = 1, 2, \dots, T, \quad (3)$$

are more Gaussian than the corresponding residuals in the forward direction,  $\{\epsilon_t\}_{t=1}^T$  [Hernández-Lobato *et al.*, 2011]. In particular, the magnitude of the cumulants of order higher than 2 is reduced:

$$\begin{aligned} \kappa_n(\tilde{\epsilon}_t) &= c_n(\phi) \kappa_n(\epsilon_t), \quad n > 0 \\ c_n(\phi) &= (-\phi)^n + (1 - \phi^2)^n (1 - \phi^n)^{-1}, \end{aligned} \quad (4)$$

where  $\kappa_n(\cdot)$  denotes the  $n$ -th cumulant. For a stationary AR(1) processes with  $\phi \neq 0$  and  $|\phi| < 1$  this implies that

$$|\kappa_n(\tilde{\epsilon}_t)| \leq |\kappa_n(\epsilon_t)|, \quad \forall n > 2. \quad (5)$$

## Time Reversal in Vector Autoregressive Models

Consider a  $d$ -dimensional autoregressive model

$$\mathbf{X}_t = \mathbf{A} \mathbf{X}_{t-1} + \epsilon_t, \quad \epsilon_t \perp \mathbf{X}_{t-1}, \quad (6)$$

where  $\mathbf{A}$  is a matrix whose eigenvalues are within the unit circle in the complex plane and  $\epsilon_t$  is i.i.d noise. A linear fit of the time-reversed process is:

$$\mathbf{X}_t = \tilde{\mathbf{A}} \mathbf{X}_{t+1} + \tilde{\epsilon}_t, \quad (7)$$

with  $\tilde{\epsilon}_t$  time-reversed residuals. The matrix of autoregressive coefficients for the reversed time series,  $\tilde{\mathbf{A}}$ , needs not be equal to  $\mathbf{A}$ . Both matrices are related by:

$$\tilde{\mathbf{A}} = \Sigma \mathbf{A}' \Sigma^{-1}, \quad \Sigma = \mathbb{E}[\mathbf{X}_t \mathbf{X}_t'] \quad (8)$$

One can define the time-reversed residuals of a linear fit

$$\tilde{\epsilon}_t \equiv \mathbf{X}_t - \tilde{\mathbf{A}} \mathbf{X}_{t+1}. \quad (9)$$

- $\tilde{\epsilon}_t$  is Gaussian and  $\tilde{\epsilon}_t \perp \mathbf{X}_{t+1}$  if and only if  $\epsilon_t$  is multi-dimensional Gaussian i.i.d noise.
- Otherwise,  $\tilde{\epsilon}_t$  is not Gaussian i.i.d noise and  $\tilde{\epsilon}_t \not\perp \mathbf{X}_{t+1}$ .

By analogy to the one-dimensional case we conjecture that the (multi-dimensional) distribution of backward residuals  $\{\tilde{\epsilon}_t\}$  is more Gaussian than the distribution of forward residuals  $\{\epsilon_t\}$  and propose to use this to determine the direction of time.

## Statistical Tests for the Detection of the Arrow of Time

**Tests Based on Independence:** The residuals in the each direction satisfy  $\epsilon_t \perp \mathbf{X}_{t-1}$  and  $\tilde{\epsilon}_t \not\perp \mathbf{X}_{t+1}$ . Thus, tests of independence, e.g. the HSIC [Gretton *et al.*, 2008], can be used to determine the correct direction of time [Peters *et al.*, 2009].

**Tests Based on Measures of Gaussianity:** The test performs a linear fit in the original and in the reversed ordering. The ordering in which the residuals are less Gaussian is then chosen. A measure of deviation from the Gaussian distribution is used.

## A measure of Deviation from a Bi-variate Gaussian Distribution

**Theorem:** Let  $\epsilon^x$  and  $\epsilon^y$  be two random variables. Let  $\mathbf{Z}(\alpha) \equiv \epsilon^x \cos \alpha + \epsilon^y \sin \alpha$ .  $\mathbf{Z}(\alpha)$  is normal  $\forall \alpha \in [0, \pi]$  if and only if the joint distribution of  $\epsilon^x$  and  $\epsilon^y$  is normal.

Inspired by this theorem we use the integrated excess of kurtosis to estimate the deviation from the bi-variate Gaussian of the distribution of the residuals  $\epsilon_t = (\epsilon_t^x, \epsilon_t^y)$ :

$$\int |\kappa_4| \equiv \frac{1}{\pi} \int_0^\pi d\alpha |\kappa_4[\mathbf{Z}(\alpha)]|. \quad (10)$$

The computational cost is  $\mathcal{O}(N)$ , i.e., linear in the number of observations.

## Experimental Settings: Noise and Auto-correlation matrix A

$\mathbf{A} = \mathbf{P} \mathbf{D}^{-1}$  with  $\mathbf{D} = \text{diag}(\lambda_1, \lambda_2)$ .  $\lambda_1, \lambda_2$  and  $\mathbf{P}$  are fixed to specific values.

Two types of noise are considered:

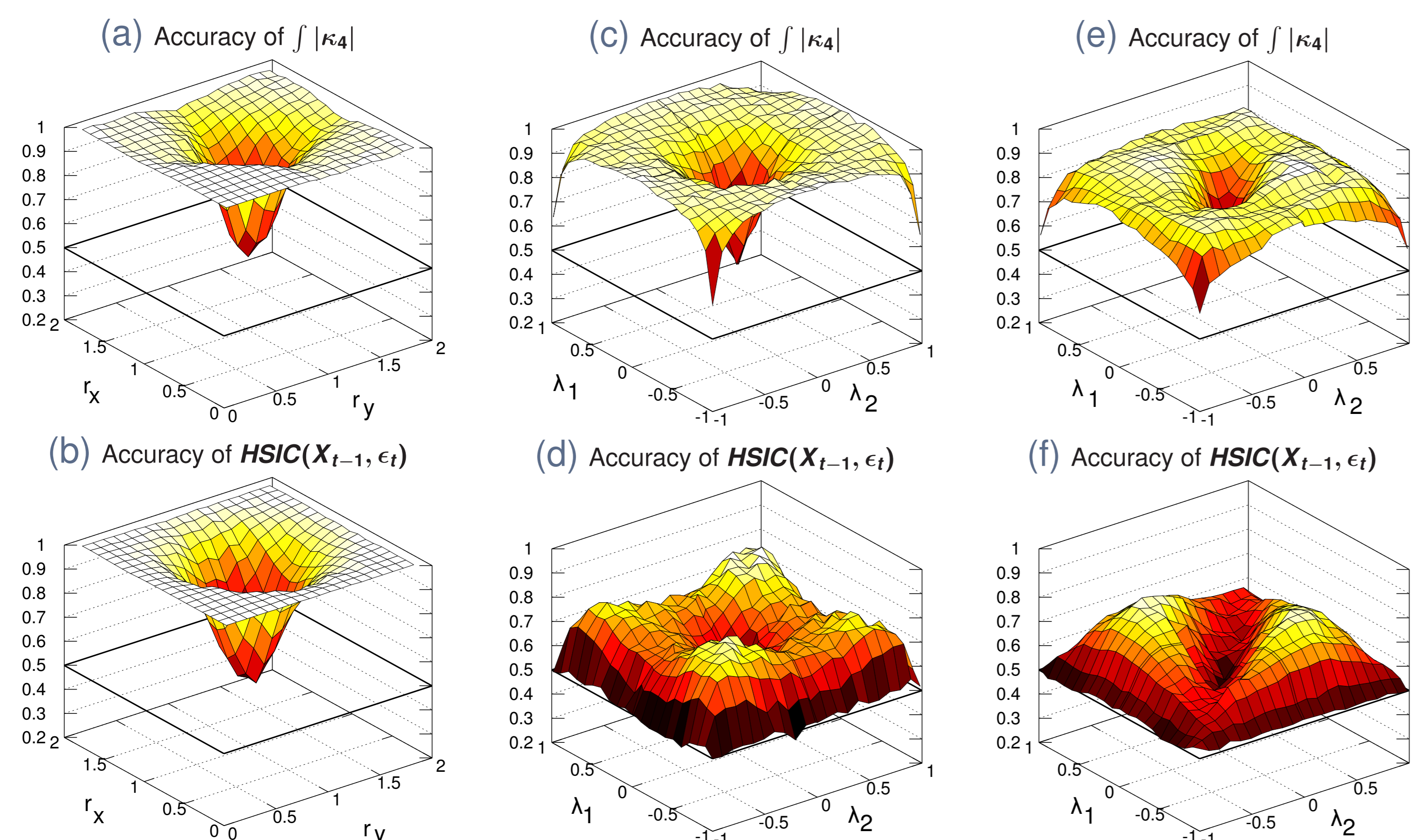
$$\epsilon_t = \begin{pmatrix} \epsilon_t^x \\ \epsilon_t^y \end{pmatrix} = \begin{pmatrix} \text{sign}(\mathbf{Z}_t^x) |\mathbf{Z}_t^x|^{r_x} \\ \text{sign}(\mathbf{Z}_t^y) |\mathbf{Z}_t^y|^{r_y} \end{pmatrix},$$

where  $(\mathbf{Z}_t^x, \mathbf{Z}_t^y)^T \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$

$\epsilon_t \sim \mathbf{C}(\Phi(\epsilon_t^x), \Phi(\epsilon_t^y); \theta)$ ,  
where  $(\epsilon_t^x, \epsilon_t^y)^T \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$ .  $\mathbf{C}(\cdot, \cdot; \theta)$  denotes a Frank copula with parameter  $\theta$  and  $\Phi(\cdot)$  is the cdf of a normal Gaussian.

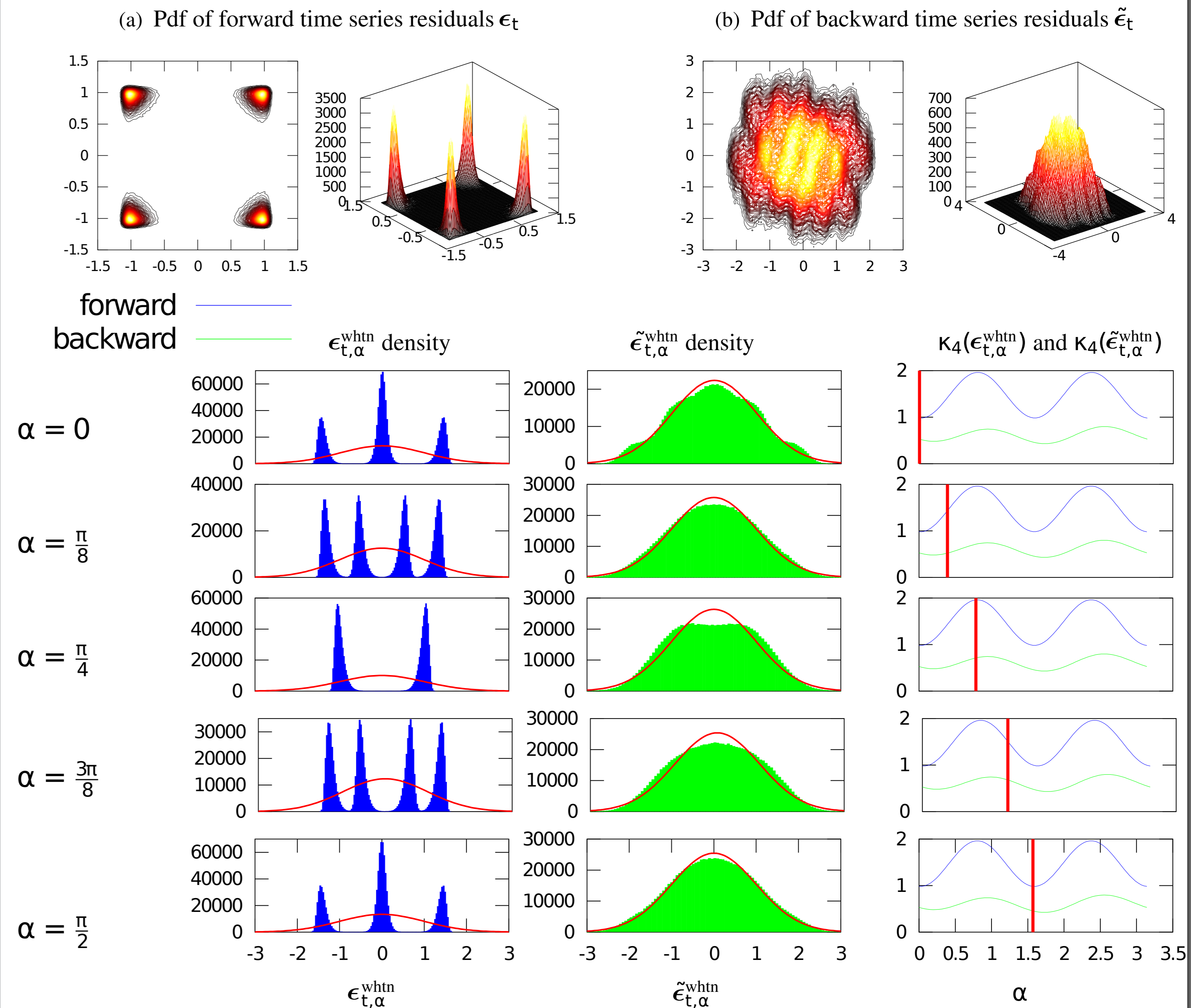
$r_x$  or  $r_y$  determine the level of non-Gaussianity of the marginals, from fully Gaussian ( $r_x = r_y = 1$ ) to leptokurtic ( $r_x > 1$  and  $r_y > 1$ ) or platokurtic ( $r_x < 1$  and  $r_y < 1$ ). The second type of noise has Gaussian marginals but non-Gaussian dependencies.

## Synthetic Experiments: Results



In experiments (a) and (b)  $\mathbf{P} = \mathbf{I}$  and  $\lambda_1 = \lambda_2 = (\sqrt{5} - 1)/2$ . In experiments (c) and (d)  $r_x = r_y = 0.75$  and  $\mathbf{P} \neq \mathbf{I}$ . In these experiments the first type of noise is employed. In experiments (e) and (f)  $\mathbf{P} = \mathbf{I}$  and the second type of noise is employed with  $\theta = 10$ .

## Gaussianization Effect in the Time-reversed Residuals



## Conclusions

- A statistical test determines the direction of time of a multi-variate time series generated by a  $\text{VAR}_d(\mathbf{1})$ . The direction of time is the one in which the residuals are less Gaussian.
- A measure of discrepancy between the distribution of the residuals from a multi-variate Gaussian distribution has been defined.
- Tests based on measures of Gaussianity show better performance than tests based on measures of independence. Furthermore, they are more efficient.
- If  $\mathbf{X}$  and  $\mathbf{Y}$  are identically distributed random variables and the relation between them is linear, the the proposed test can be used to determine whether  $\mathbf{X}$  causes  $\mathbf{Y}$ .

## References

- J.M. Hernández-Lobato, P. Morales-Mombiela, and A. Suárez. Gaussianity measures for detecting the direction of causal time series. In 22nd IJCAI, 2011.
- Peters, D. Janzing, A. Gretton, and B. Schölkopf. Detecting the direction of causal time series. In ICML, pages 801-808. ACM, 2009.
- A. Gretton, K. Fukumizu, C. H. Teo, L. Song, B. Schölkopf, and A. Smola. A kernel statistical test of independence. In NIPS 20, pages 585-592. MIT Press, 2008.